

CV 4101 AY 2016-2017

i. a) 2 DOFs -  $u_4'$ ,  $v_4'$

b) Member 1  $c=1, s=0, \frac{AE}{L} = 400\,000$

$$K_1' = \begin{pmatrix} x & x & x & x \\ x & x & x & x \\ \hline x & x & 400\,000 & 0 \\ x & x & 0 & 0 \end{pmatrix}$$

Member 2  $c=0, s=1, \frac{AE}{L} = 400\,000$

~~$$K_2' = \begin{pmatrix} x & x & x & x \\ x & x & x & x \\ \hline x & x & 0 & 0 \\ x & x & 0 & 400\,000 \end{pmatrix}$$~~

$$K_2' = \begin{pmatrix} x & x & x & x \\ x & x & x & x \\ \hline x & 0 & 0 & 0 \\ x & -400\,000 & 0 & 400\,000 \end{pmatrix}$$

↳ for part (c)

Member 3  $c = \frac{1}{\sqrt{2}}, s = \frac{1}{\sqrt{2}}, \frac{AE}{L} = 400\,000$

$$K_3' = \begin{pmatrix} x & x & x & x \\ x & x & x & x \\ \hline x & x & 200\,000 & 200\,000 \\ x & x & 200\,000 & 200\,000 \end{pmatrix}$$

Assembling

$$\begin{pmatrix} R_{1x} \\ R_{1y} \\ R_{2x} \\ R_{2y} \\ R_{3x} \\ R_{3y} \\ -100 \\ 200 \end{pmatrix} = \begin{matrix} \\ \\ \\ \\ \text{column 6} \\ \downarrow \\ 0 \\ -400\,000 \end{matrix} \begin{pmatrix} 600\,000 & 200\,000 \\ 200\,000 & 600\,000 \end{pmatrix} \begin{pmatrix} u_4' \\ v_4' \end{pmatrix}$$

$$\begin{pmatrix} -100 \\ 200 \end{pmatrix} = \begin{pmatrix} 600\,000 & 200\,000 \\ 200\,000 & 600\,000 \end{pmatrix} \begin{pmatrix} u_4' \\ v_4' \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} u_4' \\ v_4' \end{pmatrix} = \begin{pmatrix} -3.125 \times 10^{-4} \\ 4.375 \times 10^{-4} \end{pmatrix} \text{ (m)}$$

c)  $v_4' = 2.1875 \times 10^{-4} \text{ m}$

$$\begin{pmatrix} -100 \\ 200 \end{pmatrix} = \begin{pmatrix} 0 & 600\,000 & 200\,000 \\ -400\,000 & 200\,000 & 600\,000 \end{pmatrix} \begin{pmatrix} v_3' \\ v_4' \\ 2.1875 \times 10^{-4} \end{pmatrix}$$

$$\begin{pmatrix} -143.75 \\ 68.75 \end{pmatrix} = \begin{pmatrix} 0 & 600\,000 \\ -400\,000 & 200\,000 \end{pmatrix} \begin{pmatrix} v_3' \\ v_4' \end{pmatrix}$$

$$v_3' = -2.917 \times 10^{-4} \text{ m}$$

magnitude of settlement = ~~2.917~~  $2.917 \times 10^{-4} \text{ m}$

2. a) 2 DOFs -  $\theta_2'$ ,  $v_3'$

b)  $\frac{4EI_1}{L_1} = 1600$ ,  $\frac{2EI_1}{L_1} = 800$ ,  $\frac{3EI_2}{L_2} = 1200 = \frac{3EI_2}{L_2} = \frac{3EI_2}{L_2}$

$$K_1' = \begin{pmatrix} x & x & x & x \\ x & x & x & 800 \\ x & x & x & x \\ x & x & x & 1600 \end{pmatrix}, F_{01}' = \begin{pmatrix} x \\ \frac{24 \times 1^2}{12} \\ x \\ -\frac{24 \times 1^2}{12} \end{pmatrix} = \begin{pmatrix} x \\ 2 \\ x \\ -2 \end{pmatrix}$$

$$K_2' = \begin{pmatrix} x & x & x & 0 \\ x & 1200 & -1200 & 0 \\ x & -1200 & 1200 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, F_{02}' = \begin{pmatrix} x \\ \frac{3PL}{16} \\ \frac{5P}{16} \\ 0 \end{pmatrix} = \begin{pmatrix} x \\ 7.5 \\ 7.5 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} R_{1y}' \\ M_{1\theta}' \\ R_{2y}' \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{matrix} \text{column 4} \\ \downarrow \\ 800 \\ \text{column 5} \\ \downarrow \\ 2800 \quad -1200 \\ -1200 \quad 1200 \end{matrix} \begin{pmatrix} 0 \\ 0 \\ 0 \\ \theta_2' \\ v_3' \\ x \end{pmatrix} + \begin{pmatrix} x \\ 2 \\ x \\ 2.5 \\ 7.5 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 2800 & -1200 \\ -1200 & 1200 \end{pmatrix} \begin{pmatrix} \theta_2' \\ v_3' \end{pmatrix} + \begin{pmatrix} 2.5 \\ 7.5 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} \theta_2' \\ v_3' \end{pmatrix} = \begin{pmatrix} -6.25 \times 10^{-3} \text{ rad} \\ -0.0125 \text{ m} \end{pmatrix}$$

c)  $M_{1\theta}' = 800 \theta_2' + 2 = 0.01 \times \frac{200 \times 2}{1} = 4$

$$\theta_2' = 2.5 \times 10^{-3} \text{ rad}$$

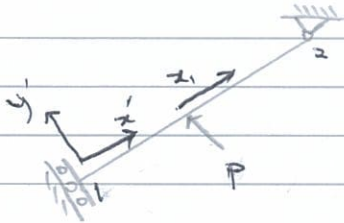
$$\begin{pmatrix} 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 2800 & -1200 \\ -1200 & 1200 \end{pmatrix} \begin{pmatrix} \theta_2' \\ v_3' \end{pmatrix} + \begin{pmatrix} \frac{3P}{16} - 2 \\ \frac{5P}{16} \end{pmatrix} \rightarrow \begin{pmatrix} 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 2800 & -1200 \\ -1200 & 1200 \end{pmatrix} \begin{pmatrix} 2.5 \times 10^{-3} \\ v_3' \end{pmatrix} + \begin{pmatrix} \frac{3P}{16} - 2 \\ \frac{5P}{16} \end{pmatrix}$$

$$-5 = -1200 v_3' + \frac{3P}{16} \dots (1)$$

$$3 = 1200 v_3' + \frac{5P}{16} \dots (2)$$

$$P = -4 \text{ KN}$$

3. a)



1 DOF -  $v_1'$

$$K_1' = \begin{pmatrix} \times & \times & \times & \times & \times & 0 \\ \times & \frac{3EI}{L^3} & \times & \times & \times & 0 \\ \times & \times & \times & \times & \times & 0 \\ \times & \times & \times & \times & \times & 0 \\ \times & \times & \times & \times & \times & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} R_{1x'} \\ 0 \\ M_1 \theta \\ R_{2x'} \\ R_{2y'} \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ v_1' \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ -\frac{11P}{16} \\ \times \\ 0 \\ \times \\ 0 \end{pmatrix}$$

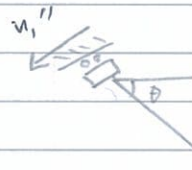
column 2  
+  
 $\frac{3EI}{L^3}$

$$F_1' = \begin{pmatrix} 0 \\ -\frac{11P}{16} \\ \times \\ 0 \\ \times \\ 0 \end{pmatrix}$$

$$0 = \frac{3EI}{L^3} v_1' - \frac{11P}{16}$$

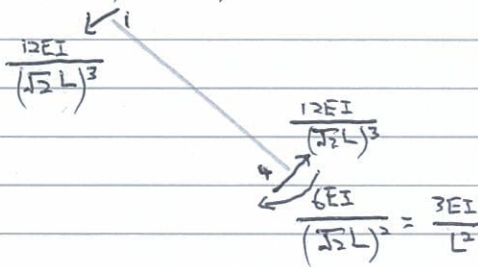
$$\therefore v_1' = \frac{11PL^3}{48EI}$$

b) 3 DOFs -  $u_1'', v_4', \theta_4'$

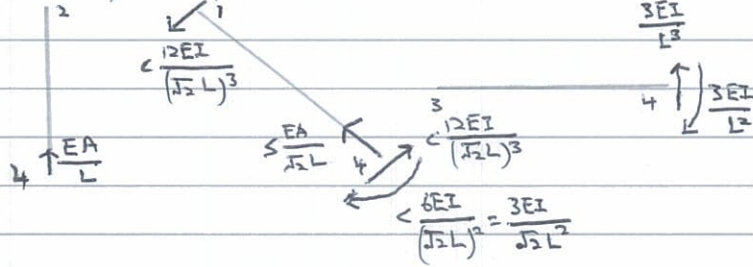


$$s = \sin \theta, c = \cos \theta$$

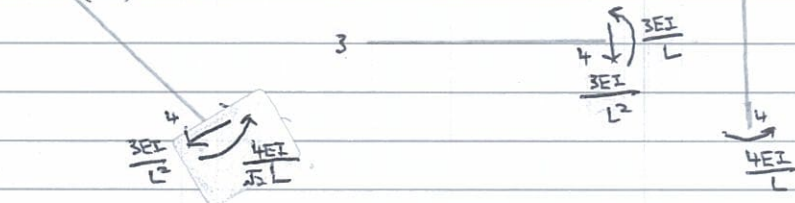
$u_1'' = 1, v_4' = 0, \theta_4' = 0$



$v_4' = 1, u_1'' = 0, \theta_4' = 0$



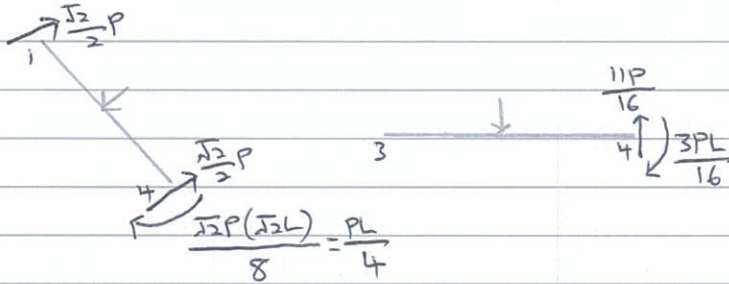
$\theta_4' = 1, u_1'' = 0, v_4' = 0$





$$K_{pp}' = \begin{pmatrix} 12 \frac{EI}{(\sqrt{2}L)^3} & \frac{12EI}{(\sqrt{2}L)^3} & -\frac{3EI}{L} \\ \frac{12EI}{(\sqrt{2}L)^3} & \frac{EA}{L} + 5 \frac{EA}{\sqrt{2}L} + \frac{12EI}{(\sqrt{2}L)^3} + \frac{3EI}{L^3} & -\frac{3EI}{\sqrt{2}L^2} - \frac{3EI}{L^2} \\ -\frac{3EI}{L^2} & -\frac{3EI}{\sqrt{2}L^2} - \frac{3EI}{L^2} & (7 + \frac{4}{\sqrt{2}}) \frac{EI}{L} \end{pmatrix} \begin{matrix} \leftarrow u_1'' \\ \leftarrow v_4' \\ \leftarrow \theta_4' \end{matrix}$$

$$= \begin{pmatrix} 4.2426 \frac{EI}{L^3} & 3 \frac{EI}{L^3} & -3 \frac{EI}{L^2} \\ 3 \frac{EI}{L^3} & 6.4749 \frac{EI}{L^3} & -5.1213 \frac{EI}{L^2} \\ -3 \frac{EI}{L^2} & -5.1213 \frac{EI}{L^2} & 9.8284 \frac{EI}{L} \end{pmatrix}$$

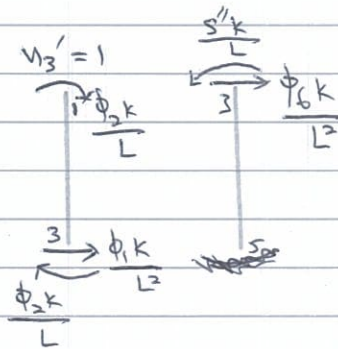
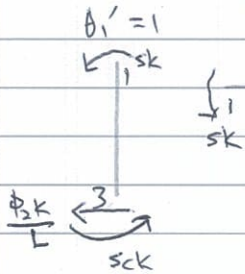


$$F_{pk}' = \begin{pmatrix} -\frac{\sqrt{2}}{2}P \\ \frac{\sqrt{2}}{2}P + \frac{11P}{16} \\ -\frac{PL}{4} - \frac{3PL}{16} \end{pmatrix} = \begin{pmatrix} -\frac{\sqrt{2}}{2}P \\ \frac{19}{16}P \\ -\frac{7}{16}PL \end{pmatrix}$$

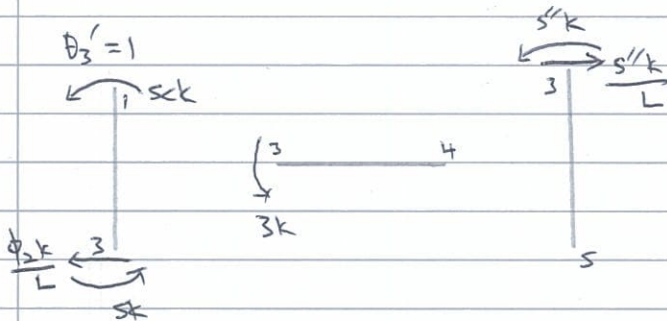
$$\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 4.2426 \frac{EI}{L^3} & 3 \frac{EI}{L^3} & -3 \frac{EI}{L^2} \\ 3 \frac{EI}{L^3} & 6.4749 \frac{EI}{L^3} & -5.1213 \frac{EI}{L^2} \\ -3 \frac{EI}{L^2} & -5.1213 \frac{EI}{L^2} & 9.8284 \frac{EI}{L} \end{pmatrix} \begin{pmatrix} u_1'' \\ v_4' \\ \theta_4' \end{pmatrix} + \begin{pmatrix} -\frac{\sqrt{2}}{2}P \\ \frac{19}{16}P \\ -\frac{7}{16}PL \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} u_1'' \\ v_4' \\ \theta_4' \end{pmatrix} = \begin{pmatrix} 0.4320 \\ -0.4151 \\ -0.039976/L \end{pmatrix} \frac{PL^3}{EI}$$

4. a) 3 DOFs -  $\theta_1'$ ,  $u_3'$ ,  $\theta_3'$  ( $u_3' = u_4'$ )



$$k = \frac{EI}{L}$$



$$K_{pp}' = \begin{pmatrix} 2s_k & -\frac{\phi_2 k}{L} & s_k k \\ -\frac{\phi_2 k}{L} & \frac{\phi_1 k}{L^2} + \frac{\phi_6 k}{L^2} & \frac{s' k}{L} - \frac{\phi_2 k}{L} \\ s_k k & \frac{s' k}{L} - \frac{\phi_2 k}{L} & (3 + 5s')k \end{pmatrix} \begin{matrix} \leftarrow \theta_1' \\ \leftarrow u_3' \\ \leftarrow \theta_3' \end{matrix}$$

$$P_{12} = P_{13} = P_{35} = P/\sqrt{2}$$

$$P_{E,12} = P_{E,13} = P_{E,35} = \frac{\pi^2 EI}{L^2}, \text{ so } P_{12} = P_{13} = P_{35} = P$$

$$|k_{PP'}| = 2sk \left| \begin{array}{cc} \frac{\phi_1 k}{L} + \frac{\phi_6 k}{L} & \frac{s''k}{L} - \frac{\phi_2 k}{L} \\ \frac{s''k}{L} - \frac{\phi_2 k}{L} & (3+s+s'')k \end{array} \right| - \left( -\frac{\phi_2 k}{L} \right) \left| \begin{array}{cc} -\frac{\phi_2 k}{L} & \frac{s''k}{L} - \frac{\phi_2 k}{L} \\ sck & (3+s+s'')k \end{array} \right| + sck \left| \begin{array}{cc} -\frac{\phi_2 k}{L} & \frac{\phi_1 k}{L} + \frac{\phi_6 k}{L} \\ sck & \frac{s''k}{L} - \frac{\phi_2 k}{L} \end{array} \right| = 0$$

$$\begin{aligned} &= \frac{2sk^3}{L^2} \left[ (\phi_1 + \phi_6)(3+s+s'') - (s'' - \phi_2)^2 \right] + \frac{\phi_2 k^3}{L^2} \left[ -\phi_2(3+s+s'') - sc(s'' - \phi_2) \right] \\ &+ sc \frac{k^3}{L^2} \left[ -\phi_2(s'' - \phi_2) - sc(\phi_1 + \phi_6) \right] = 0 \end{aligned}$$

$$\therefore (3+s+s'')(2s\phi_1 + 2s\phi_6 - \phi_2^2) - 2sc\phi_2(s'' - \phi_2) - (sc)^2(\phi_1 + \phi_6) - 2s(s'' - \phi_2)^2 = 0$$

$$P = 0.40, s = 3.4439, c = 0.6242, s'' = 2.1021, f(s, c) = 25.1708$$

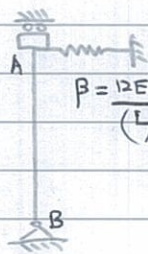
$$P = 0.42, s = 3.4144, c = 0.6321, s'' = 2.0501, f(s, c) = -2.1926$$

$$P_{cr} = 0.40 + \frac{0 - 25.1708}{-2.1926 - 25.1708}(0.42 - 0.40)$$

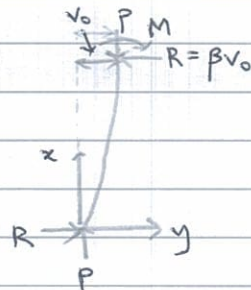
$$= 0.4184$$

$$\therefore P_{cr} = 0.4184 P_E \times \sqrt{2} = 0.5917 \frac{\pi^2 EI}{L^2}$$

4. b)



$$\beta = \frac{12EI}{(L/2)^3} = \frac{96EI}{L^3}$$



$$EIv'' = -Pv + \beta v_0 x$$

$$v'' + \omega^2 v = \frac{\beta v_0}{EI} x, \quad \omega = \sqrt{\frac{P}{EI}}$$

$$v = A \sin \omega x + B \cos \omega x + \frac{\beta v_0}{P} x$$

$$\rightarrow v'(x) = A \omega \cos \omega x - B \omega \sin \omega x + \frac{\beta v_0}{P}$$

Apply boundary condition,

$$v(0) = 0, \quad B = 0$$

$$v'(L) = 0, \quad A \omega \cos \omega L + \frac{\beta v_0}{P} = 0$$

$$A = -\frac{\beta v_0}{P \omega \cos \omega L}$$

$$v(L) = v_0$$

$$-\frac{\beta v_0}{P \omega \cos \omega L} \sin \omega L + \frac{\beta v_0}{P} L = v_0$$

$$-\frac{96}{(\omega L)^3} \tan \omega L + \frac{96}{(\omega L)^2} = 1$$

$$\phi^3 + 96(\tan \phi - \phi) = 0, \quad \phi = \omega L$$

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